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Rumor Spreading and Invasion Percolation

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Abstract

We study the models of rumor spreading and invasion bond percolation aimed at the revelation of possible connections between them. Rumor spreading model describes the dissemination of a rumor due to the periodical repetition of sequential phone calls, whereas the invasion bond percolation refers to the spread of liquid in the porous environment. During a round of the rumor spreading, each node performs a call only once, meanwhile transmitting all the information that it knows at the moment of the call to its neighbors. The rumor reaches the receiver node during one round if there is a chain of successive calls between the source of the rumor and that node. The sequence of calls is taken uniformly at random from the set of all possible sequences (permutations of nodes). We compare the propagation of the rumor spreading with the invasion bond percolation in order to put forth necessary improvements of the percolation rules to map one model onto another, and vice versa.

Keywords: Gossip problem, Information dissemination, Invasion percolation.

1. Introduction and Models

The spreading of rumors and invasion percolation are core problems in two different fields: the theory of dissemination of information [1]–[17] and the theory of flow in a porous media [18]–[23]. Both problems concern with the stochastic growth of clusters: the cluster of informed individuals in the first case and the cluster of invaded sites in the second one. Here, we consider two models typical for each problem and establish a link between them.

Among the variety of formulations of the first problem, we choose the random phone call model [19] defined on the so called communication graph G(V, E) with the set of vertices V and the set of edges E. Vertices V denote the set of players, the edges E denote possible connections between the players by phone calls. Whenever a connection is established, the rumor can be transmitted from one player (if she holds the rumor) to another player (if she does not hold the rumor yet). In [19], the authors considered the model where the players communicate in parallel during communication rounds. It means that any information received in a round cannot be forwarded to another player in the same round. The aim is to spread all rumors from all players to others. The problem was to find an algorithm using only $O(\ln |V|)$ rounds and $O(|E| \ln \ln |E|)$ calls.

In this paper, we concentrate on kinetics of the rumor propagation on the communication graph G(V, E). To this end, we investigate the effect of sequential communications when a rumor can be translated through a chain of random calls during one round. Correspondingly, each round in our model is a finite time interval containing all possible connections $e_i \in E, i = 1, 2, \ldots, |E|$, which happen exactly once at moments t(i), where $t(i) \equiv t(e_i)$ is the moment of connection e_i in the current round. We assume that all moments $t(i), i = 1, 2, \ldots, |E|$ are distinct and uniformly distributed between the beginning and the end of each round. The effect of sequential communications leads to a specific pattern of the cluster growth, which is similar to the invasion percolation. However, the rules of growth of the clusters of informed players and invaded sites in the percolation problem are not completely identical.

Let $v^* \in V$ be a fixed player who is the origin of the rumor and $P = (p_1, p_2, \dots, p_{|E|})$ is a permutation of numbers $(1, 2, \dots, |E|)$ such that $t(p_1) < t(p_2) < \dots < t(p_{|E|})$ in the first round. Denoting by $e_{ij} \in E$ the edge connecting adjacent vertices $i \in V$ and $k \in V$ and $k \in V$ as the sequence of connections $e_{i_1i_2}, e_{i_2i_3}, \dots, e_{i_{k-1}i_k}$. The path between $k \in V$ and $k \in V$ as the sequence of connections $k \in V$ and $k \in V$ as the rumor if $k \in V$ and $k \in V$ as the rumor if $k \in V$ and $k \in V$ as the sequence of connections $k \in V$ and $k \in V$ as the sequence of connections $k \in V$ and $k \in V$ as the sequence of connections $k \in V$ and $k \in V$ as the sequence of connections $k \in V$ and $k \in V$ in the first round if there exists a conducting path between $k \in V$ and $k \in V$ and $k \in V$ and $k \in V$ in the first round if there exists a conducting path between $k \in V$ and $k \in V$ are $k \in V$ and $k \in V$ an

The subset $V_1 \subset V$ of vertices reachable from v^* during the first round represents the set of players getting informed due to permutation of calls P. The quantity of interest is the number of informed players $|V_1|_P$ and its average taken over all permutations $\langle |V_1| \rangle = \sum_P |V_1|_P Prob|V_1|_P$. A conducting path between two arbitrary vertices is not necessarily self-avoiding. Indeed, the path may contain one or more loops, which appear if both adjacent vertices i and j in connection e_{ij} belonging to the path are already informed before the moment $t(e_{ij})$. We can coin such a connection as non-informative in contrast to a informative connection that conducts the rumor. The exclusion of non-informative connections from all conducting paths removes all possible loops. Then, the remaining informative connections form a connected graph, which is a tree spanning the subset of informed players V_1 and is rooted at v^* . By definition, the first round is complete if all possible connections $e_i \in E, i = 1, 2, \ldots, |E|$ happened exactly once. Alternatively, we can say that the round is complete only if subset V_1 contains all possible vertices reachable from v^* for the given permutation P.

When the first round is over, the next rounds start consecutively with the same sequence of connections t(i), i = 1, 2, ..., |E|. Players receiving the rumor in the first round can serve as origins of the same rumor for the second round. As above, the rumor is spreading along the conducting paths started at the boundary vertices of subset V_1 . (As usual, we call a vertex $v \in V$ the boundary vertex of a subset $V_1 \subset V$ if $v \in V_1$ and at least one of the nearest neighbors of v in graph G(V, E) does not belong to V_1). The collection of informative connections in the second round forms a graph, which is a forest with roots at the boundary vertices of V_1 . The forest spans the subset of players V_2 being informed during the second complete round.

Continuing the process round by round, we obtain a sequence of subsets of players V_i , $i = 1, 2, \ldots$ characterized by the size $|V_i|_P$ and the average size $\langle |V_i| \rangle$ for each round and by the average correlations between the rounds. The process is finished when all players V become informed with the rumor. The question is the average number of rounds needed for the total spreading of the rumor.

The associated problem, invasion percolation, has many formulations as well [20]. We

choose from them a popular version, namely, the invasion bond percolation model [21]. Similar to the first problem, we start with the graph G(V, E) with sets of vertices and edges V and E. We assign random numbers $p_{ij} \in [0,1]$ to each edge $e_{ij} \in E$. Invasion percolation is a process of successive occupation of the vertices and edges of G(V, E). At the first step, one occupies a randomly chosen vertex $v^* \in V$. Then, one considers all edges adjacent to v^* and occupies the edge with the smallest p_{ij} together with the second vertex belonging to it. At subsequent steps, one finds the empty edge with the smallest p_{ij} connected to the occupied vertices, and checks whether this edge connects two occupied vertices or not. In the former case, the edge is called trapped since it is situated between two occupied vertices. If the edge is not trapped, it becomes occupied together with the empty vertex it connects with the occupied cluster. In this way, one constructs a graph of occupied edges and vertices $T \subset G(V, E)$, which is a tree spanning the cluster of occupied vertices at the given stage.

The described model was introduced by Barabasi [22] and called the invasion bond percolation model with a local trapping rule to distinguish it from the ordinary invasion bond percolation where the trapped edges can be occupied as well as the non-trapped ones. Barabasi proved that the trapping rule does not affect the scaling and dynamic properties of growing clusters of occupied vertices and, therefore, the two models belong to the same universality class. Moreover, the construction of tree T in the Barabasi's model coincides with the Prim's algorithm for finding the shortest spanning tree of a weighted random graph [23]. In the next section, we consider a modification of the Prim's algorithm to map it into the model of transmission of rumors. The subsequent sections will be devoted to the exact solutions of the latter model for simplified graphs G(V, E) and the comparison of cluster growth in models of transmission of rumors and the invasion bond percolation.

2. The Modified Model of Invasion Percolation

The main difference between the models of transmission of rumors and the invasion bond percolation is the monotonic character of the invasion process, which is not subdivided into finite time periods appearing in the propagation of rumors. The invasion process continues permanently and stops when all vertices of graph G(V, E) become occupied. The propagation of rumors is intermitted at the end of each complete round when all players reachable for the given permutation of calls become informed. To eliminate the difference, we introduce a modified model of invasion percolation (or a modified Prim's algorithm).

As before, we begin with the graph G(V, E) and the set of random weights $p(i, j) \in [0, 1]$ assigned to each edge $e_{ij} \in E$. Again, we choose a vertex $v^* \in V$ and consider it as the starting point of a growing cluster. The cluster grows by successive adding new occupied edges. The occupation of edge e_{ij} means the occupation of adjacent vertices i and j as well. The addition process yields two restrictions:

(a) Each new edge we are going to occupy connects two vertices, one of which belongs to the cluster and the other does not.

This rule guaranties that the growing cluster is a tree. Of two connected edges of the tree, we call a *predecessor* the edge that is closer to the starting point. The other edge is the *successor*.

(b) Each new occupied edge being a successor, has the weight larger than its predecessor. The edges yielding both rules (a) and (b) are called eligible for the growth. The modified model of invasion percolation is defined by the following steps. The first step is the occupation of the starting vertex v^* . Given a connected cluster of edges and vertices C(i) obtained after

i steps, $i = 1, 2, \ldots$, we select the set of edges E(i) eligible for the growth (for edges adjacent to the starting point, the rule (b) is omitted). Choose in the set E(i) the edge e_{ij} with minimal weight p(i, j) and add it to the cluster of occupied edges and vertices. In this way, we obtain the cluster C(i + 1).

If, after some number of steps i_1 , there are no edges eligible for growth, we fix the cluster $C(i_1)$ and start the next round of growth. To this end, we take the same set of random weights $p(i,j) \in [0,1]$ and consider the boundary vertices of the set $C(i_1)$ as the starting points for the next round. The cluster of edges and vertices obtained after i-th step of the second round is denoted by $C(i_1,i)$. For each step of the second round, we define the set $E(i_1,i)$ of edges eligible for growth and choose among them the edge e_{ij} with minimal weight p(i,j). The second round continues during a number of steps i_2 until one is able to find edges eligible for growth. The set of edges and vertices occupied during the second round is $C(i_1,i_2)$. The process proceeds round by round until the set of vertices in $C(i_1,i_2,\ldots,i_{max})$ coincides with that in G(V,E).

We get a modified model of invasion bond percolation displaying an intermittence of the invasion process. In order to get the correspondence between the introduced model and the random call model, we restrict the length of each round in the latter model to the unit time interval. Then, we can identify the moments of calls t(i), i = 1, 2, ..., |E| with the random numbers $p_{ij} \in [0,1]$ assigned to each edge $e_{ij} \in E$. The condition that all p_{ij} are distinct is not essential since p_{ij} are continuous variables. The condition of completeness of each round is identical for both models if one takes into account the ability of a cluster to grow during the round.

3. The One-dimensional Lattice

In this section, we illustrate the considered models with a simplified example, where the communication graph G(V, E) is a finite one-dimensional lattice. The set of vertices $V \subset \mathbb{Z}$ representing the players consists of L+1 lattice points $i \in V, i=1,2,\ldots,L+1$. The set of edges E represents L connections $e_j \in E$ between the neighboring vertices j and j+1, $j=1,2,\ldots,L$.

The origin of the rumor is the first player i=1, and $t(j) \equiv t(e_j)$ are the moments of calls used by the connections $e_j, j=1,2,\ldots,L$. The order of calls corresponds to the permutation $P=(p_1,p_2,\ldots,p_L)$ such that $t(p_1) < t(p_2) < \cdots < t(p_L)$. The rumor reaches the player k_1+1 during the first round and does not propagate further if

$$t(1) < t(2) < \dots < t(k_1), t(k_1) > t(k_1 + 1).$$
 (1)

Consider $k_1 + 1$ numbers $t(1), t(2), \ldots, t(k_1 + 1)$. Among $(k_1 + 1)!$ permutations of these numbers, only one is ordered as

$$t(1) < t(2) < \dots < t(k_1) < t(k_1 + 1)$$
 (2)

with probability $1/(k_1+1)!$. The order (2) can be broken and converted into (1) in k_1 ways by replacing any of k_1 first numbers with $t(k_1+1)$. Therefore, the probability of order (1) is k_1 times greater than that of (2) and we get

$$Prob(k_1) = \frac{k_1}{(k_1 + 1)!}. (3)$$

The rumor reaches the player $k_1 + 1$ during the first round and the player $k_1 + k_2 + 1$ during the second round but does not propagate further if

$$t(1) < t(2) < \cdots < t(k_1); \quad t(k_1 + 1) < t(k_1 + 2) < \cdots < t(k_1 + k_2)$$

but

$$t(k_1) > t(k_1 + 1)$$
: $t(k_1 + k_2) > t(k_1 + k_2 + 1)$

To find the probability $Prob(k_1, k_2)$, one has to exclude $Prob(k_1 + k_2)$ from the product of two probabilities $1/k_1!$ and $Prob(k_2)$:

$$Prob(k_1, k_2) = \frac{k_2}{k_1!(k_2+1)!} - \frac{k_1 + k_2}{(k_1 + k_2 + 1)!}.$$

The calculation of further probabilities $Prob(k_1, k_2, ..., k_n)$ is a direct application of the inclusion-exclusion principle. For instance,

$$Prob(k_1, k_2, k_3) = k_3/(k_1!k_2!(1+k_3)!) - k_3/((k_1+k_2)!(1+k_3)!) - (k_2+k_3)/(k_1!(1+k_2+k_3)!) + (k_1+k_2+k_3)/(1+k_1+k_2+k_3)!$$

Knowing the probabilities $Prob(k_1, k_2, ..., k_i)$, we can calculate the expected values $\langle k_i \rangle$ in the limit $L \to \infty$:

$$\langle k_i \rangle = \sum_{k_1=1,\dots,k_i=1}^{\infty} k_i Prob(k_1, k_2, \dots, k_i)$$

The first several results are:

$$\langle k_1 \rangle = e - 1$$

$$\langle k_2 \rangle = e^2 - 2e$$

$$\langle k_3 \rangle = \frac{3e}{2} - 3e^2 + e^3$$

$$\langle k_4 \rangle = -\frac{2e}{3} + 4e^2 - 4e^3 + e^4$$

$$\langle k_5 \rangle = \frac{5e}{24} - \frac{10e^2}{3} + \frac{15e^3}{2} - 5e^4 + e^5$$

the numerical values of which are:

$$\langle k_1 \rangle = 1.718281828...$$

$$\langle k_2 \rangle = 1.952492442...$$

$$\langle k_3 \rangle = 1.995791369...$$

$$\langle k_4 \rangle = 2.000038850...$$

$$\langle k_5 \rangle = 2.000057578...$$

One can expect that $\langle k_n \rangle \to 2$ when $n \to \infty$. To prove this conjecture, it is sufficient to find the generating function (see Appendix)

$$R(x) = \sum_{m=1}^{\infty} \langle k_m \rangle x^m = \frac{1-x}{1-x \exp(1-x)}$$

and verify that

$$R(x) \sim 2/(1-x) + O(x-1)$$

in the vicinity of the point x = 1.

4. Conclusion

In our works [24]–[29], toppling of grains at nodes (graph vertices in Abelian sandpile model) was interpreted as a transmission of the full information accumulated in a vertex, activated at the moment, to all its neighbors (k-broadcast). Taking into account that activation of vertices is performed according to a predefined random order, and a single time tact is defined to be a discrete time interval (equal to the number of vertices) of activation of all the vertices, it is necessary to estimate the average number of tacts required for the full information exchange/transmission.

The exact formula for the average number of tacts for (n, n) lattices has not yet been derived. Nevertheless, based on the required number of experimental data, statistical curves of the main characteristics have been obtained, the study of which made it possible to set up a hypothesis (research methods and results are not included in this paper) that the average number of tacts is 0.25 n.

Study of the models of rumor spreading and invasion bond percolation, aimed at the revelation of possible connections between them, is performed. It is shown that the rumor reaches the receiver node during one round if there is a chain of successive calls between the source of the rumor and that node. Given that the sequence of calls is taken uniformly at random from the set of all possible sequences, analytical properties of information dissemination have been investigated.

The results obtained make it possible to improve the percolation rules aimed at mapping one model onto another, and vice versa. Future work will be dedicated to the comparative analysis between rumor spreading and invasion bond percolation models.

5. Appendix

We define a set of all partitions $\mathbb{P}(\{k_1, k_2, \dots, k_n\})$ of a set of n integers $\{k_1, k_2, \dots k_n\}$ as a set of the following 2^{n-1} subsets

$$\mathbb{P}(\{k_1\}) = \{\{k_1\}\}\$$

$$\mathbb{P}(\{k_1, k_2\}) = \{ \{\{k_1\}, \{k_2\}\}, \{\{k_1, k_2\}\} \}$$

In general, recursively, if the set of m subsets of $\{k_1, k_2, \ldots, k_n\}$ $S_i, i = 1, 2, \ldots, m$, is a partition

$$\{S_1, S_2, \dots, S_m\} \in \mathbb{P}(\{k_1, k_2, \dots, k_n\})$$
 (4)

then

$$\{S_1, S_2, \dots, S_m, \{k_{n+1}\}\} \in \mathbb{P}(\{k_1, k_2, \dots, k_{n+1}\}) \text{ and }$$

 $\{S_1, S_2, \dots, S_{m-1}, S_m \cup \{k_{n+1}\}\} \in \mathbb{P}(\{k_1, k_2, \dots, k_{n+1}\})$ (5)

are also partitions. Each of S_i , i = 1, 2, ..., m in (4) and (5) is a set of k integers $S = \{l_1, l_2, ..., l_k\}$, where $l_i \in \mathbb{N}$, i = 1, 2, ..., k. We denote |S| = k and $||S|| = l_1 + l_2 + \cdots + l_k$. Then, (using the inclusion-exclusion principle), we obtain a sum over all elements of $\mathbb{P}(\{k_1, k_2, ..., k_n\})$:

$$\operatorname{Prob}(k_1, k_2, \dots, k_n) = \sum_{m=1}^{n} \sum_{\{S_1, S_2, \dots, S_m\} \in \mathbb{P}(\{ \mathbb{k}_{l \times 1}, \mathbb{k}_{l \times 1}, \mathbb{k}_{l \times 1}, \mathbb{k}_{l \times 1} \})} \frac{(-1)^{n+m}}{\|S_1\|! \|S_2\|! \cdots \|S_{m-1}\|!} \frac{\|S_m\|}{(\|S_m\| + 1)!}.$$

Therefore, the average value of k_n is

$$\langle k_n \rangle = \sum_{k_1=1}^{\infty} \sum_{k_2=1}^{\infty} \dots \sum_{k_n=1}^{\infty} k_n \operatorname{Prob}(k_1, k_2, \dots, k_n)$$

$$= \sum_{m=1}^{n} \sum_{\{S_1, S_2, \dots, S_m\} \in \mathbb{P}(\{\not \Vdash, \not\models, \dots, \kappa\})} (-1)^{n+m} \alpha_{|S_1|} \alpha_{|S_2|} \cdots \alpha_{|S_m|}, \qquad (6)$$

where $\alpha_n, n > 0$ is the *n*-fold sum

$$\alpha_n = \sum_{k_1=1}^{\infty} \sum_{k_2=1}^{\infty} \cdots \sum_{k_n=1}^{\infty} \frac{1}{(k_1 + k_2 + \dots + k_n)!}$$
 (7)

To calculate (7) with $n = 1, 2, \ldots$, we introduce the generating function

$$f_n(x) = \sum_{k_1=1}^{\infty} \sum_{k_2=1}^{\infty} \cdots \sum_{k_n=1}^{\infty} \frac{x^{k_1+k_2+\cdots+k_n}}{(k_1+k_2+\cdots+k_n)!}.$$

The derivative of $f_n(x)$ can be expressed in the following way

$$\frac{d f_n(x)}{d x} = \sum_{k_1=1}^{\infty} \sum_{k_2=1}^{\infty} \cdots \sum_{k_n=1}^{\infty} \frac{x^{k_1+k_2+\cdots+k_n-1}}{(k_1+k_2+\cdots+k_n-1)!}$$

$$= \sum_{k_1=1}^{\infty} \sum_{k_2=1}^{\infty} \cdots \sum_{k_{n-1}=1}^{\infty} \sum_{k_n=0}^{\infty} \frac{x^{k_1+k_2+\cdots+k_n}}{(k_1+k_2+\cdots+k_n)!}$$

$$= f_n(x) + f_{n-1}(x). \tag{8}$$

We multiply both sides of the recursive differential equation (8) by z^n and take the sum over $n = 2, 3, \ldots$. Introducing the generating function of the sequence of functions $f_n(x)$:

$$F(z,x) = \sum_{n=1}^{\infty} f_n(x)z^n,$$

and taking into account that

$$f_1(x) \equiv \sum_{k_1=1}^{\infty} \frac{x^{k_1}}{k_1!} = e^x - 1,$$

we obtain a differential equation for F(z, x):

$$\frac{\partial F(z,x)}{\partial x} = (z+1)F(z,x) + z \tag{9}$$

with initial conditions F(z,0) = 0. The solution of (9) is

$$F(z,x) = \frac{z}{z+1} \left(e^{x(z+1)} - 1 \right),$$

which can be expanded over variables x and z:

$$F(z,x) = \sum_{k=1}^{\infty} \frac{z(z+1)^{k-1}}{k!} x^k = \sum_{k=1}^{\infty} \sum_{n=1}^{k} \frac{x^k z^n}{(n-1)!(k-n)!k} = \sum_{n=1}^{\infty} \sum_{k=n}^{\infty} \frac{x^k z^n}{(n-1)!(k-n)!k}.$$

Therefore,

$$f_n(x) = \frac{1}{(n-1)!} \sum_{k=0}^{\infty} \frac{x^{n+k}}{k!(n+k)} = \frac{1}{(n-1)!} {}_0^x \tau^{n-1} e^{\tau} \tau.$$

Thus, we obtain an exact expression for α_n

$$\alpha_n = f_n(1) = (-1)^n + e \sum_{p=1}^n \frac{(-1)^{n+p}}{(p-1)!},$$

which allows one to calculate the values of α_n for various n:

$$\alpha_1 = e - 1,$$
 $\alpha_2 = 1,$ $\alpha_3 = \frac{1}{2}(e - 2),$ $\alpha_4 = \frac{3-e}{3},$ $\alpha_5 = \frac{1}{8}(3e - 8),$ $\alpha_6 = \frac{1}{30}(30 - 11e).$

Using the fact that

$$\frac{1}{e} = \sum_{n=0}^{\infty} \frac{(-1)^p}{p!},$$

we obtain an alternative representation of α_n :

$$\alpha_n = e \sum_{p=0}^{\infty} \frac{(-1)^p}{(p+n)!} = \frac{e}{n!} - \frac{e}{(n+1)!} + \frac{e}{(n+2)!} - \cdots$$

Note that

$$\frac{e}{n!} - \frac{e}{(n+1)!} < \alpha_n < \frac{e}{n!},$$

i.e.,

$$\frac{n}{n+1}\frac{e}{n!} < \alpha_n < \frac{e}{n!}.$$

Therefore, the asymptotics of α_n for large n is

$$\alpha_n \simeq \frac{e}{n!}, \quad n \gg 1.$$

Now, we can rewrite the expression (6) for $\langle k_n \rangle$ in the following form

$$\langle k_n \rangle = \sum_{\sigma_1 = 0}^{\infty} \sum_{\sigma_2 = 0}^{\infty} \cdots \sum_{\sigma_n = 0}^{\infty} \delta \left(\sum_{i=1}^n i \sigma_i, n \right) \prod_{i=1}^n \left((-1)^{1+i} \alpha_i \right)^{\sigma_i} \frac{\left(\sum_{i=1}^n \sigma_i \right)!}{\sigma_1! \sigma_2! \cdots \sigma_n!}.$$

The corresponding generating function is

$$R(x) = 1 + \sum_{n=1}^{\infty} \langle k_n \rangle x^n = \sum_{\sigma_1 = 0}^{\infty} \sum_{\sigma_2 = 0}^{\infty} \cdots \left(\prod_{i=1}^{\infty} \frac{\left((-1)^{1+i} \alpha_i \right)^{\sigma_i}}{\sigma_i!} \right) \left(\sum_{i=1}^{\infty} \sigma_i \right)! \ x^{\sum_{i=1}^{\infty} i \sigma_i}.$$

To calculate R(x), we introduce another generating function

$$D(x,z) = \sum_{\sigma_1=0}^{\infty} \sum_{\sigma_2=0}^{\infty} \cdots \left(\prod_{i=1}^{\infty} \frac{\left((-1)^{1+i} \alpha_i \right)^{\sigma_i}}{\sigma_i!} \right) z^{\sum_{i=1}^{\infty} \sigma_i} x^{\sum_{i=1}^{\infty} i \sigma_i},$$

which can be rewritten as

$$D(x,z) = \prod_{i=1}^{\infty} \left(\sum_{\sigma=0}^{\infty} \frac{((-1)^{1+i}\alpha_i)^{\sigma} z^{\sigma} x^{i\sigma}}{\sigma!} \right)$$
$$= \prod_{i=1}^{\infty} \exp\left\{ (-1)^{1+i}\alpha_i x^i z \right\}$$
$$= \exp\left\{ z \sum_{i=1}^{\infty} (-1)^{1+i}\alpha_i x^i \right\}$$

The function D(x, z) is the series

$$D(x,z) = \sum_{p=0}^{\infty} \frac{G(x)^p}{p!} z^p,$$

where

$$G(x) = \sum_{i=1}^{\infty} (-1)^{1+i} \alpha_i x^i$$

$$= \sum_{i=1}^{\infty} \left(-1 + e \sum_{j=1}^{i} \frac{(-1)^{j-1}}{(j-1)!} \right) x^i$$

$$= \frac{x}{x-1} + e \sum_{j=1}^{\infty} \left(\frac{(-1)^{j-1}}{(j-1)!} \sum_{i=j}^{\infty} x^i \right)$$

$$= \frac{x}{x-1} + \frac{e}{1-x} \sum_{j=1}^{\infty} \frac{(-1)^{j-1} x^j}{(j-1)!}$$

$$= \frac{x}{x-1} \left(1 + e^{1-x} \right)$$

On the other hand, the function R(x) can be expressed by G(x):

$$R(x) = \sum_{p=0}^{\infty} G(x)^p = \frac{1}{1 - G(x)} = \frac{1 - x}{1 - xe^{1 - x}}.$$

$$R(x) \simeq \frac{2}{1-x} + O(x-1)$$

Therefore,

$$\lim_{n\to\infty}\langle k_n\rangle=2.$$

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Քամբասանքի տարածումը և ներթափանցողական պերկոլացիա

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Ամփոփում

Մենք ուսումնասիրում ենք բամբասանքի տարածման և կողային ներթափանցողական պերկոլացիաների մոդելները՝ նպատակ ունենալով բացահայտել դրանց հավանական կապվածությունը։ Բամբասանքի տարածման մոդելը նկարագրում է դրա տարածումը հաջորդական հեռախոսազանգերի պարբերաբար կրկնվելու արդյունքում, իսկ կողային ներթափանցողական պերկոլացիաների մոդելը վերաբերում է ծակոտկեն միջավայրում հեղուկի տարածմանը։ Բամբասանքի տարածման մոդելում մեկ տակտի ընթացքում յուրաքանչյուր հանգույց կատարում է միայն մեկ զանգ՝ զանգահարելու պահին իր տիրապետած ողջ տեղեկությունը փոխանցելով հարևաններին։ Ընդսմին՝ բամբասանքը մեկ փուլի ընթացքում հասնում է ստացողին՝ բամբասանքի աղբյուրի և ստացողի միջև հաջորդական զանգերի շղթայի առկայության դեպքում։ Ձանգերի հաջորդականությունն ընտրվում է բոլոր հնարավոր հաջորդականությունների շարքից՝ հավասարաչափ պատահականության սկզբունքով (հանգույցների տեղափոխություն)։ Մենք համեմատում ենք բամբասանքի տարածման մոդելը կողային ներթափանցողական պերկոլացիայի հետ՝ մոդելների փոխադարձ արտապատկերումների իրականացման նպատակով պերկոլացիայի կանոնների անհրաժեշտ բարելավումներ առաջադրելու համար։

Քանալի բառեր՝ բամբասանքի խնդիր, ինֆորմացիայի տարածում, կողային ներթափանցողական պերկոլացիա։

Распространение сплетен и инвазивная перколяция

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Аннотация

Мы изучаем модели распространения сплетен и реберной инвазивной перколяции с целью обнаружения возможной связи между ними. Модель распространения сплетен описывает распространение как вследствие изза периодического повторения последовательных телефонных звонков, в то время как реберная инвазивная перколяция относится к распространению жидкости в пористой среде. Во время одного раунда распространения слухов каждый узел выполняет вызов только один раз, при этом передавая всю информацию, доступную в момент вызова, своим соседям. Сплетня достигает узла-получателя в течение одного раунда при наличии цепочки последовательных вызовов между источником сплетни и узлом-получателем.

Последовательность вызовов выбирается равномерно случайным образом из набора всех возможных последовательностей (перестановок узлов). Мы сравниваем модель распространения сплетен с реберной инвазивной перколяцией с целью выдвижения необходимой оптимизации правил перколяции для достижения отображения одной модели на другую, и, наоборот.

Ключевые слова: проблема сплетни, распространение информации, реберная инвазивная перколяция.